

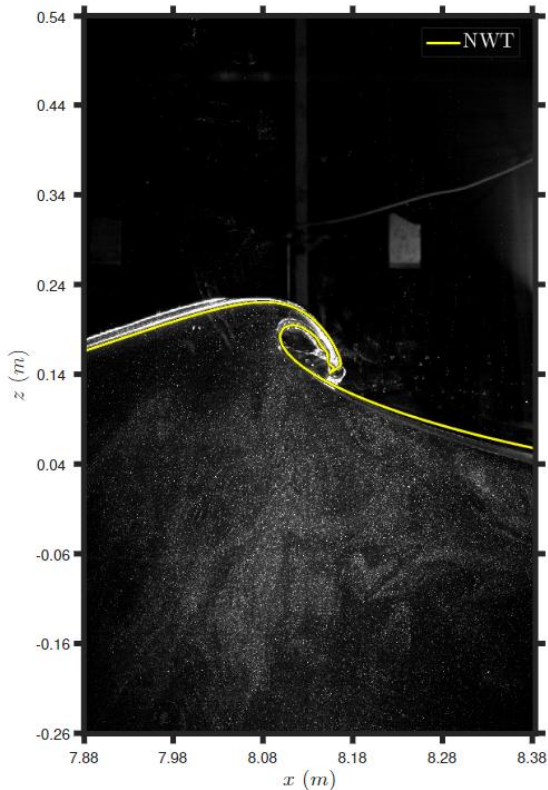
# Breaking waves in fully non-linear potential flow models

Sunil MOHANLAL<sup>1</sup>, Jeffrey C. HARRIS<sup>1</sup>, Marissa L. YATES<sup>1</sup>, Luc PASTUR<sup>2</sup>, Christophe PEYRARD<sup>1,3</sup>, Stephan T. GRILLI<sup>4</sup>

<sup>1</sup> LHSV, Ecole des Ponts, EDF R&D, Chatou <sup>2</sup> UME, ENSTA Paris, Institut Polytechnique de Paris <sup>3</sup> EDF R&D LNHE, Chatou

<sup>4</sup> Department of Ocean Engineering, University of Rhode Island, Narragansett, RI, USA

## Potential flow limits



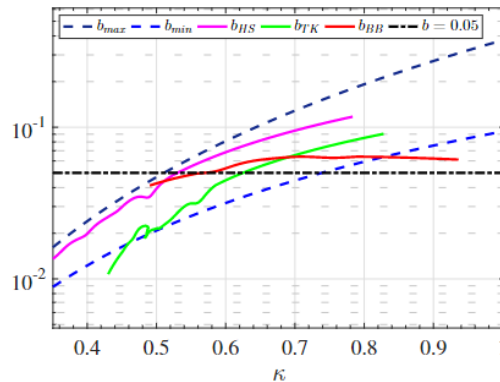
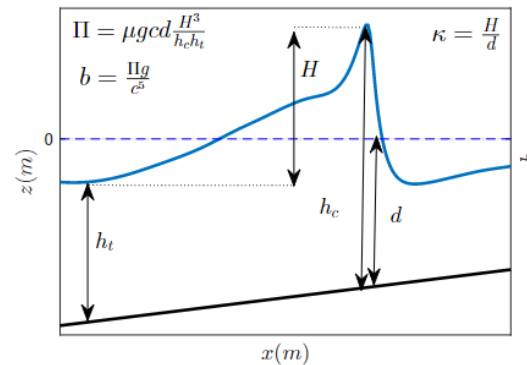
## Wave breaking implemented by a damping pressure

- Power dissipated by a breaking wave,  $\Pi(t) = \int P_b(x, y, t) \varphi_n(x, y, t) dA$
- Damping pressure,  $P_b(x, y, t) = \frac{\Pi(t) s(x, y) \varphi_n(x, y, t)}{\int s(x, y) \varphi_n(x, y, t)^2 dA}$
- The dynamic boundary condition (Bernoulli eq. on the free surface):  

$$\frac{D\varphi}{Dt} = -gz + \frac{1}{2} |\nabla\varphi|^2 - \frac{P_b}{\rho}$$

### Accurately capture the overall physics of breaking waves

- How well do we understand the physics of a breaking wave?
- How much power should be dissipated?
- When does breaking start? When does it end?



## Proposed wave breaking model applied to 2D and 3D cases

