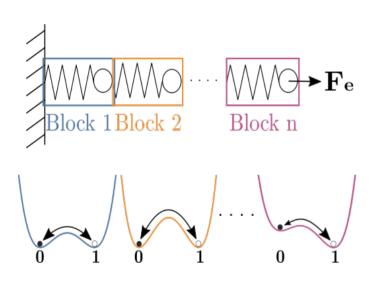
When the dynamical writing of coupled memories with reinforcement learning meets physical bounds

Laura Michel Supervisor : Frédéric Lechenault

Studied system

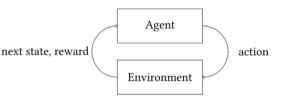


Chain of coupled bi-stable spring-mass units

Motivation

- Model for materials supporting several crystallographic phases
- Mechanical memory system for stocking
- Traditionally, quasi-static operations, known to reduce the memory capacity of the system, are used for bits manipulation

Control using RL



• RL allows to control dynamically the multi-stable chain, restoring the memory capacity of the system to its full potential



Théo Jules, Austin Reid, Karen E. Daniels, Muhittin Mungan, and Frédéric Lechenault. Delicate memory structure of origami switches. *Phys. Rev. Research*, 4, 2022.



The RL agent shares insightful knowledge

Different strategies for different regimes

Force signal (N) τ : time at which inertia becomes negligible $\propto 1/\eta$ tc : time at which the external load propagates in 8 neighboring springs $\propto \eta$ Overdamped When $\tau = t_c$, the configuration of inertia vs dissipation is 6 regime optimal and : 4 (s/bx) ماد (kg/s) ماد (s/bx) (s/bx $\eta_c \sim m^{1/2} k^{1/6} F_{\max}^{1/3}$ Optimal configuration 10^{1} 1.5 $\eta_{\rm c}\,({\rm kg/s})$ Inertial 0.6 regime 10^{0} 2 3 50 1000 Number of steps 10^{-2} 10^{-1} 10^{0} **10¹** 10^{-2} 10^{-1} 10^{0} 10^{1} \mathbf{F}_{\max} (N) m (kg)



29/03/23 - Laura Michel 2

The optimal configuration can be physically understood by introducing two typical times