Swimming dynamics and efficiency in chain diatom colonies

Julien Le Dreff¹, Blaise Delmotte¹

LadHyX, CNRS, Ecole Polytechnique, Institut Polytechnique de Paris, 91120 Palaiseau, France julien.le-dreff@polytechnique.edu

Diatom chains are cohesive assemblies of unicellular microorganisms typically found in still and fresh water [1]. While some species are passively transported by ambient currents and settle due to the weight of their dense silica shells, others use various strategies to move or self-propel [2]. One species in particular, called *Bacillaria paxillifer*, forms colonies of stacked rectangular cells that slide along each other while remaining parallel (cf. Fig. 1 a). This unique collective motion leads to beautiful and nontrivial trajectories at the colony scale (cf. Fig. 1 b-c). Using a numerical method developed to simulate rigid bodies with kinematic constraints and hydrodynamic interactions in Stokes flows [3], we show that the swimming speed of such chains changes non-monotonically with the sliding delay between adjacent cells. The swimming efficiency, as a function of sliding delay between cells, shows multiple local maxima, which contrasts with the behavior typically observed in flagellate microorganisms [4]. In addition, the optimal cell aspect ratio for swimming found with our simulation matches those observed in real diatoms.



Figure 1. a) Microscope view of two *Bacillaria paxillifer* colonies. The scale bar is 50 μ m. b-c) Simulated flow fields around two colonies with different conformations. The red line represents the trajectory of the center of mass of the colony.

Références

- 1. E. VIRGINIA ARMBRUST, The life of diatoms in the world's oceans, Nature, 459, (2009).
- 2. J. ARRIETA, R. JEANNERET, P. ROIG & I. TUVAL, On the fate of sinking diatoms : the transport of active buoyancy-regulating cells in the ocean, *Phil. Trans. R. Soc. A*, **378**, (2020).
- 3. J. J. L. HIGDON, A hydrodynamic analysis of flagellar propulsion, J. Fluid Mech., 90, (1979).
- 4. F. B. USABIAGA AND B. DELMOTTE, A numerical method for suspensions of articulated bodies in viscous flows, J. Comput. Phys., 464, (2022).